
ON THE TREATMENT AND CHALLENGES OF MODEL UNCERTAINTY

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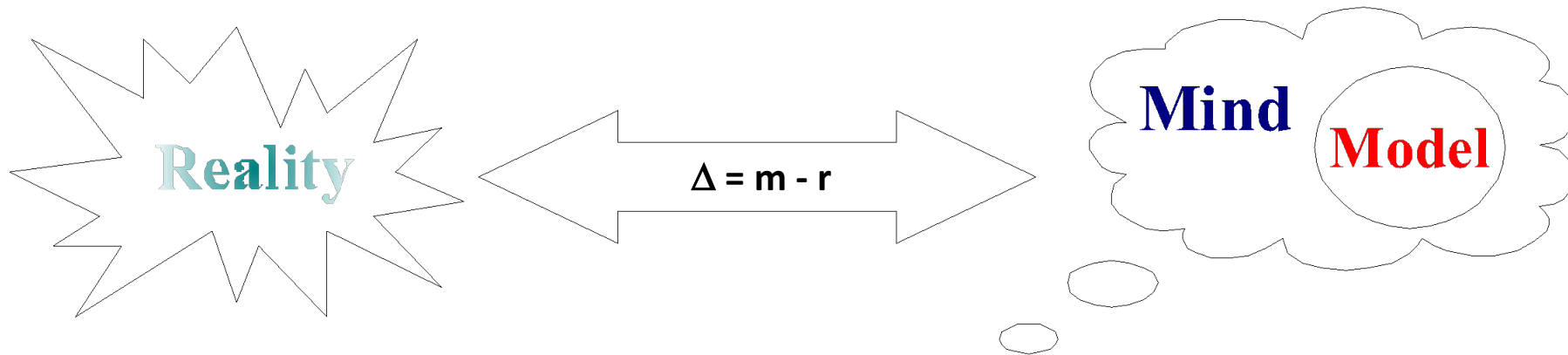
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ROADMAP

- Fundamentals:
 - Models, Model Uncertainty and Parameter Uncertainty
 - Modeling Process and Model Uncertainty
 - Model Output Uncertainty
- Operationalization of Model Uncertainty
 - Bayesian and Non-Bayesian based approaches
 - Model performance
 - Model applicability
- Challenges ahead
 - Uncertainty is uncertainty?
 - Multiple models, submodels and dependency
 - Accounting for the unexpected
 - Massive and multidimensional data

FUNDAMENTALS

MODEL ERROR AND MODEL UNCERTAINTY



MODEL UNCERTAINTY AND PARAMETER UNCERTAINTY

- Models can be characterized as having a structure (S) and a set of parameters (Θ)

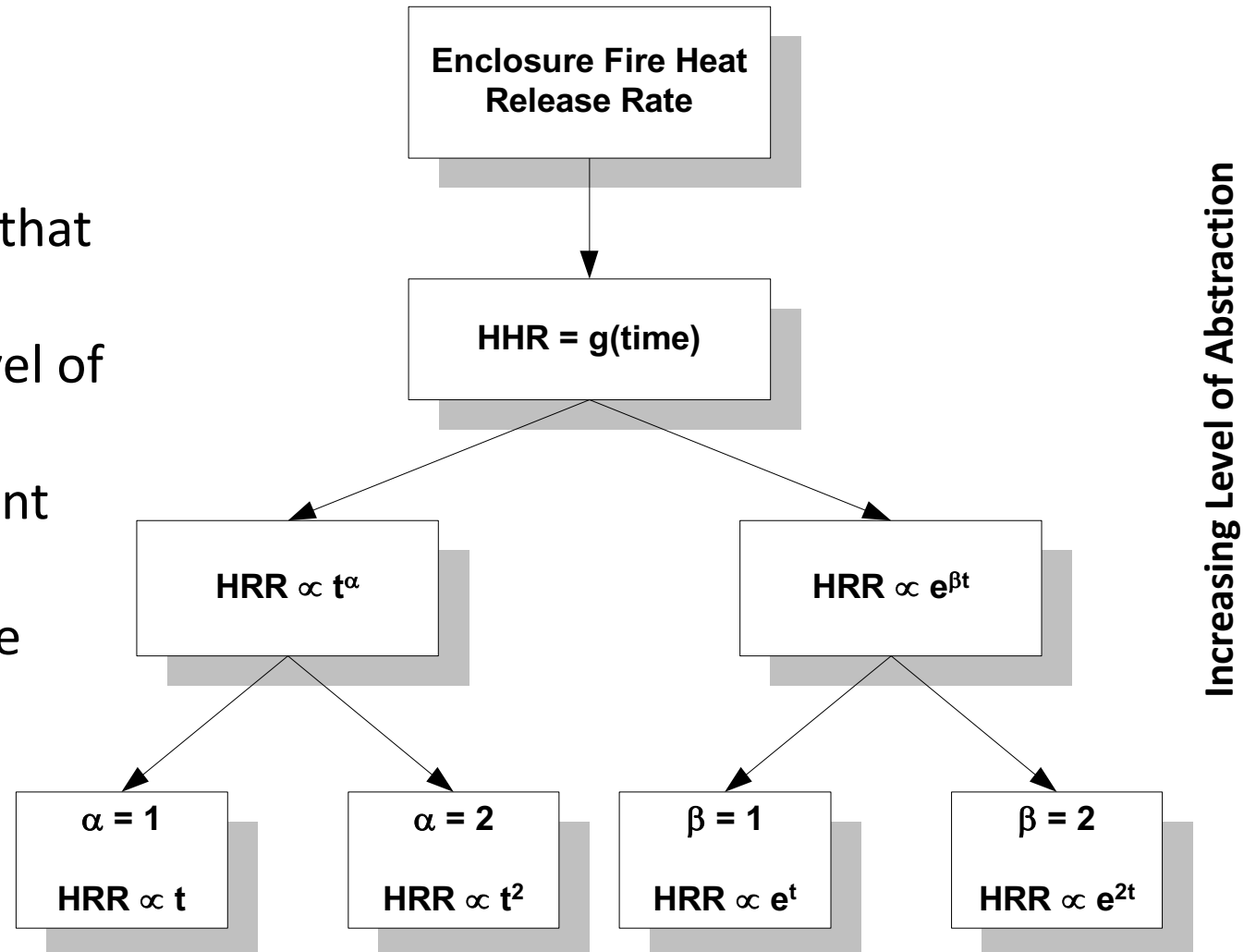
$$x = M(S, \Theta)$$

- Uncertainty attributed to the values of parameters is commonly referred to as "Parameter Uncertainty"
- Uncertainty arising from lack of confidence in model structure or alternative structures is commonly referred to as "Model Uncertainty"

MODELING PROCESS: MODEL FORM AND PARAMETERS

Parameter:

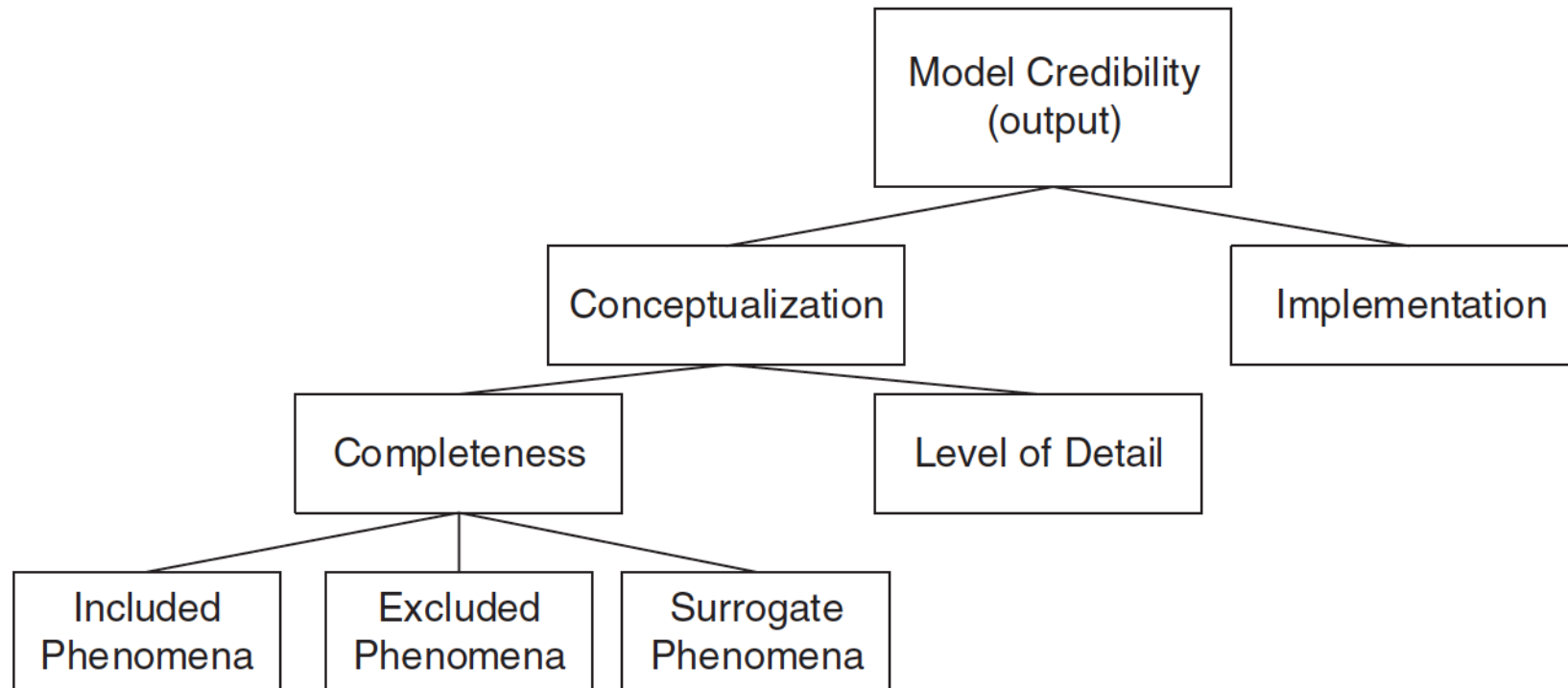
- An aspect of the model that relates it to its specific instances in the next level of the modeling process
- A parameter in the parent model can become a structural element in the child model



SOURCES OF MODEL UNCERTAINTY

- Alternative plausible hypotheses for describing the phenomena
- A single model:
 - Generally accepted but not completely validated
 - Conceptually accepted and validated but its implementation is of uncertain quality
 - Recognized to only partially cover the relevant aspects of the problem
 - Composed of sub-models of different degrees of accuracy and credibility
- Multiple models, each covering different aspects of the reality
- Surprising events, change of a known pattern

MODEL CREDIBILITY



MODEL OUTPUT UNCERTAINTY

- Uncertainty associated to the difference between the model output values and the true values of the quantities of interest (Bjerga, Aven, Zio; 2014):

$$\Delta G(X) = G(X) - Z$$

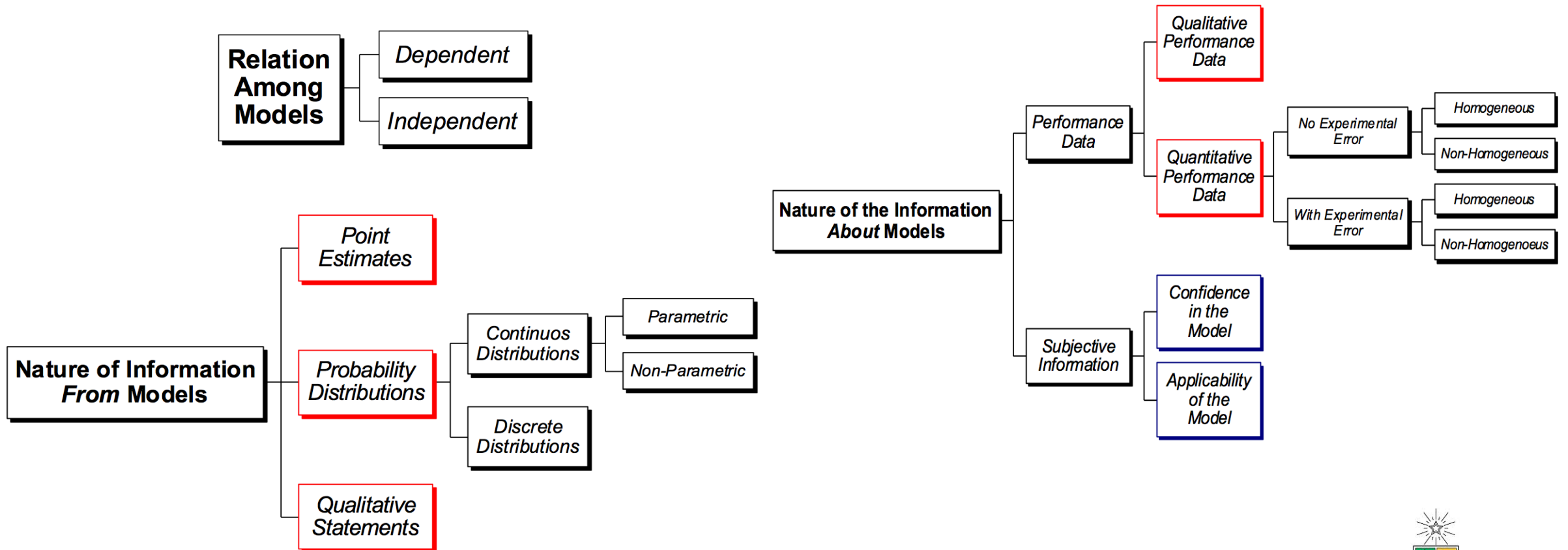
STRUCTURAL MODEL UNCERTAINTY

- Model output uncertainty results from the combination of two components:
 - Structural model uncertainty
 - Parameter uncertainty
- Structural model uncertainty:
 - Fundamentally, model uncertainty is model structural uncertainty
 - It is a source of uncertainty
 - In practice, both sources (model and parameter uncertainties) usually get confounded
 - And this is reflected in the model output error

OPERATIONALIZATION

DIFFERENT REALITIES - DIFFERENT SOLUTIONS

- Available information, context of application, objective of the analysis



UNCERTAINTY FACTOR APPROACH

- It introduces a correction factor directly on the predictions provided by a single model (Siu and Apostolakis, 1986 and 1992):

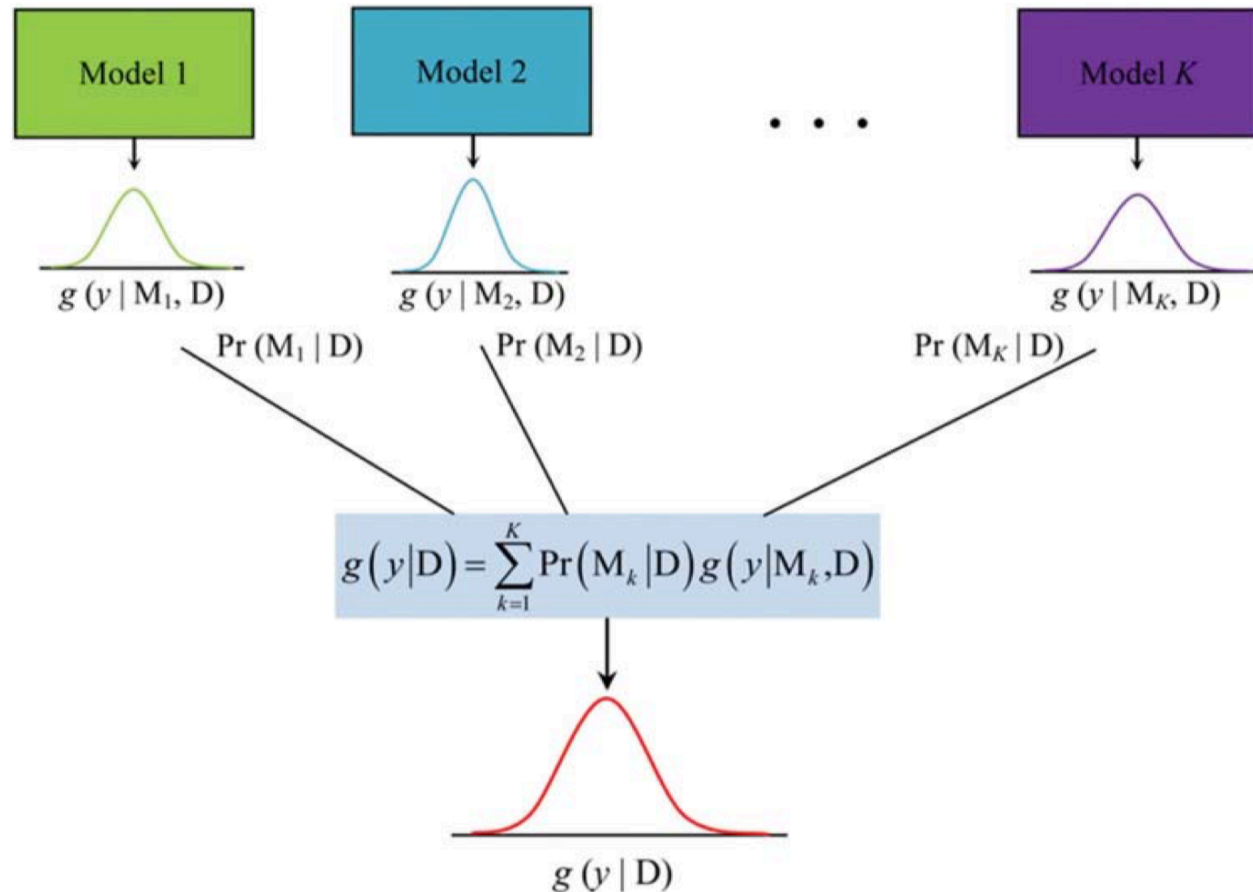
$$X = X_M - \xi_a \qquad X = X_M / \xi_m$$

- The correction factor translates the modeler's confidence in the model's M prediction X_M about the quantity of interest X

$$f(\xi_m|E) = \int_{\Lambda} f(\xi_m|\Lambda)\pi(\Lambda|E)d\Lambda$$

- It allows for the use of a model outside its intended domain of application (extrapolation)
- Usually applicable to situations where only one model is available

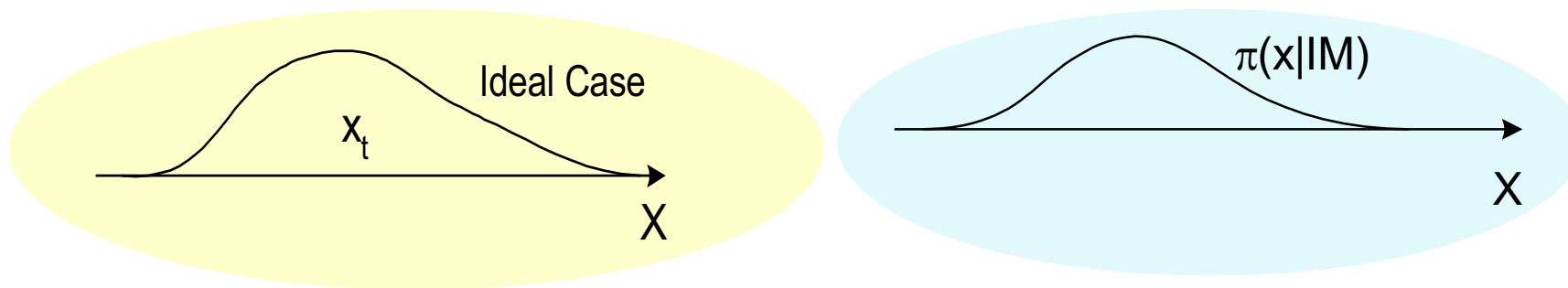
MODEL AVERAGING



- The set of models should be mutually exclusive and collectively exhaustive
- The model weights should sum up to one
- The collective exhaustiveness implies that not only the probability attributed to a model is interpreted as the probability that model M_i is “correct”, but also the “correct” model should necessarily be one of the alternate models

BAYESIAN PERSPECTIVE

- In assessing the uncertainty about X , the objective is to ensure that the true but unknown value x_t falls within some uncertainty range characterized by a probability distribution $\pi(x)$
- We could settle for a probability distribution given the available evidence relevant to the estimation of the unknown X , $\pi(x|IM)$



BAYESIAN ASSESSMENT

$$\pi(\mathbf{x} | \text{IM}) = \frac{L(\text{IM} | \mathbf{x}) \pi_0(\mathbf{x})}{\int_{\mathbf{x}} L(\text{IM} | \mathbf{x}) \pi_0(\mathbf{x}) d\mathbf{x}}$$

$$\text{IM} = (\text{IM}_1, \text{IM}_2, \dots, \text{IM}_n)$$

$$L(\text{IM} | \mathbf{x}) = L(\underline{\mathbf{x}}^* | \underline{\mathbf{D}}, \mathbf{x}) L(\underline{\mathbf{D}} | \mathbf{x})$$

Model
Estimate

Information
about Model

SINGLE MODEL

- Model M provides an estimate u^* about an unknown u
- Evidence D about the model M :

$$\pi(u | u^*, D) = \frac{L(u^* | D, u) \pi_o(u)}{\int_u L(u^* | D, u) \pi_o(u) du}$$

- With an appropriate likelihood parameterization:

$$\pi(u | u^*, D) = \frac{\left[\int_{\underline{\theta}} L(u^* | \underline{\theta}, u) \pi(\underline{\theta} | D) d\underline{\theta} \right] \pi_o(u)}{\int_u \left[\int_{\underline{\theta}} L(u^* | \underline{\theta}, u) \pi(\underline{\theta} | D) d\underline{\theta} \right] \pi_o(u) du}$$

MODEL UNCERTAINTY QUANTIFICATION IN LIGHT OF PERFORMANCE DATA

- D corresponds to the available information about M :
 - Performance data: experimental results x_1^e, \dots, x_n^e and corresponding model estimates x_1^*, \dots, x_n^*

- Additive model error:

$$E_i = x_i^* - x_i^t$$

- Likelihood:

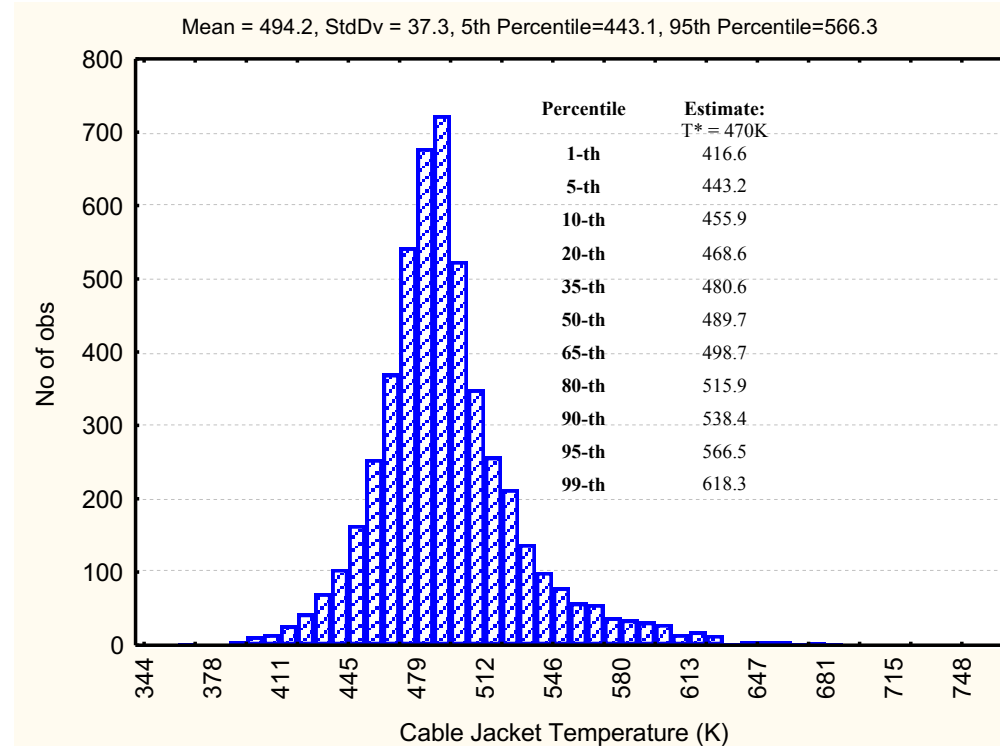
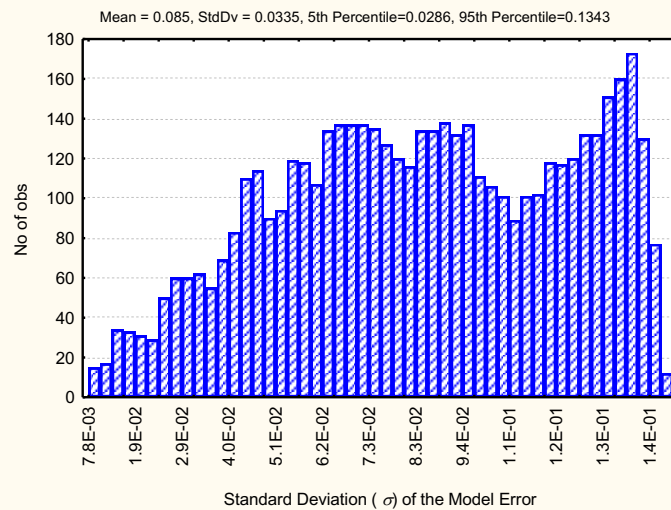
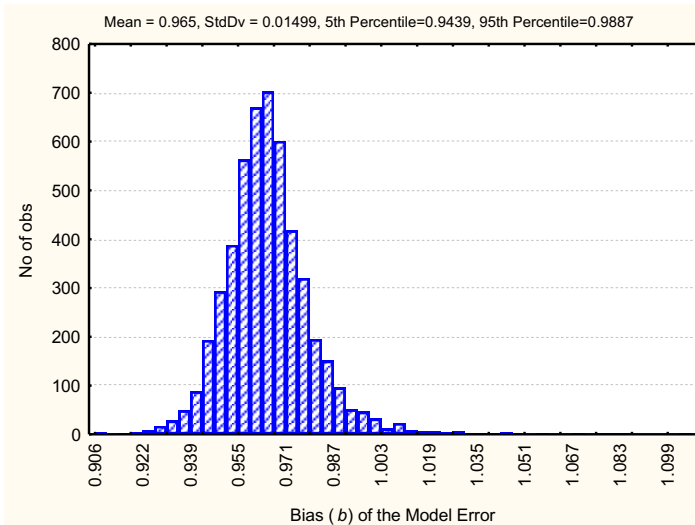
$$L(x^* | x, \underline{\theta}) = L(x^* | x, b, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{1}{2} \left(\frac{x^* - (x+b)}{\sigma} \right)^2}$$

FIRE HAZARD WITH HOMOGENEOUS PERFORMANCE DATA

- Fire hazard model for estimating cable jacket temperatures. The model provides a new estimate of 470 K at 300 seconds
- Homogeneous performance data:

Time (sec)	Cable Jacket Temperature (K)		
	Experimental Result (T^e)	Model Predictions	
		T_{gj}^p	T_{gj}^p / T_{gj}^e
60	360	375	1.042
180	425	430	1.012
300	455	470	1.033
480	505	500	0.990
720	575	520	0.904
900	575	500	0.870

FIRE HAZARD WITH HOMOGENEOUS PERFORMANCE DATA

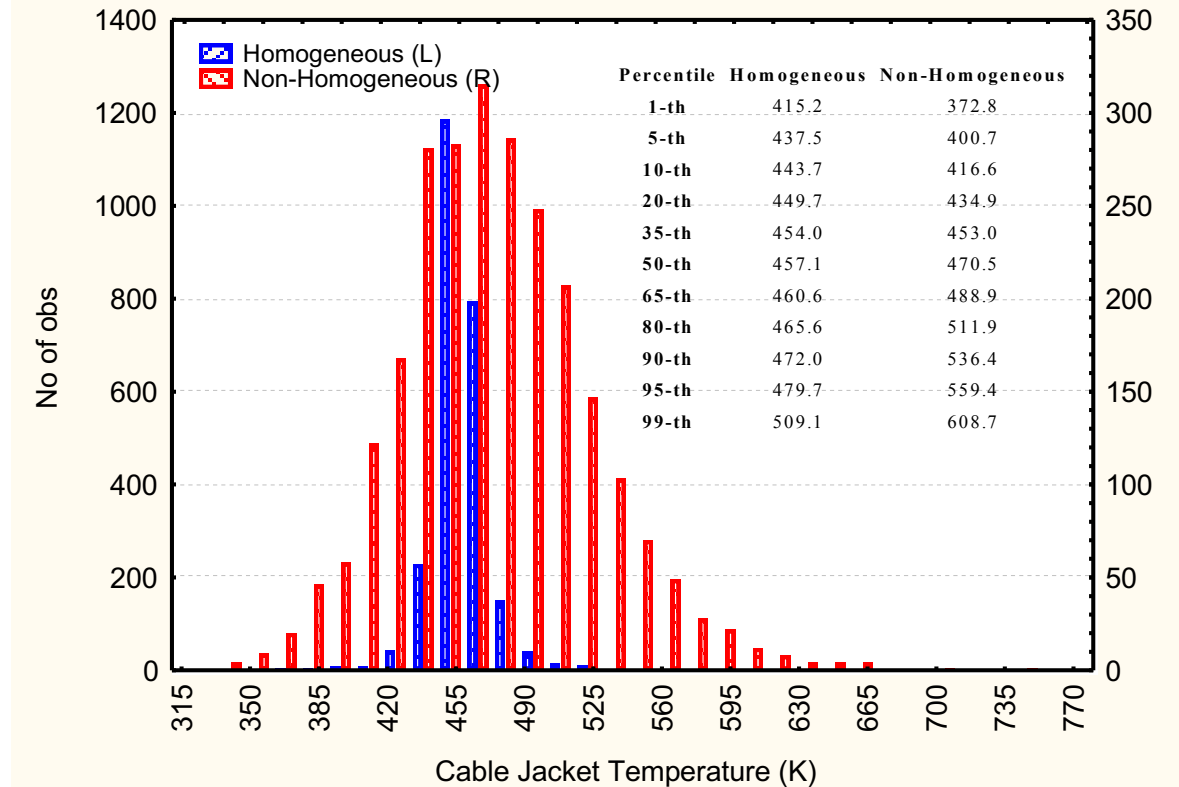


NON-HOMOGENEOUS PERFORMANCE DATA

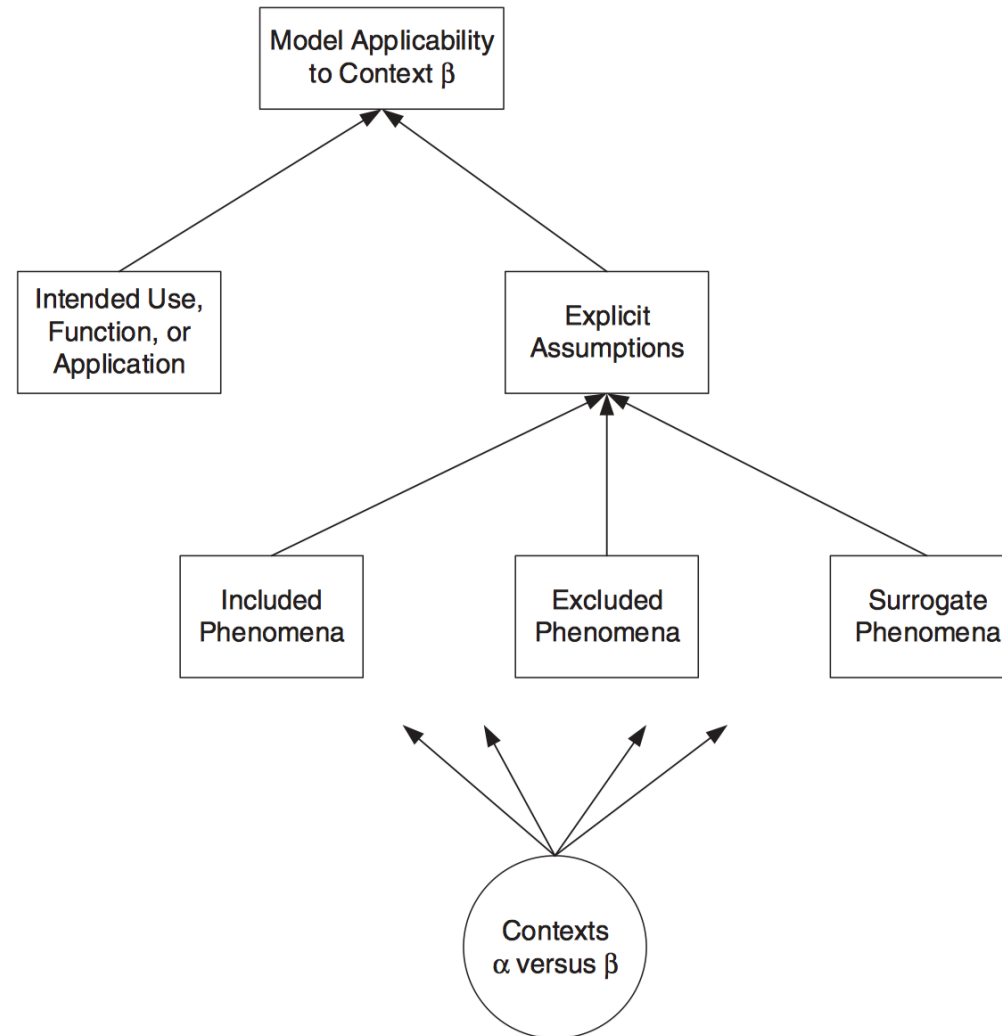
- Posterior expected distribution:

$$\pi(x|x^*, D) \propto \left[\int_{\underline{\theta}} L(x^* | \underline{\theta}, x) \bar{g}(\underline{\theta} | D) d\underline{\theta} \right] \times \pi_o(x)$$

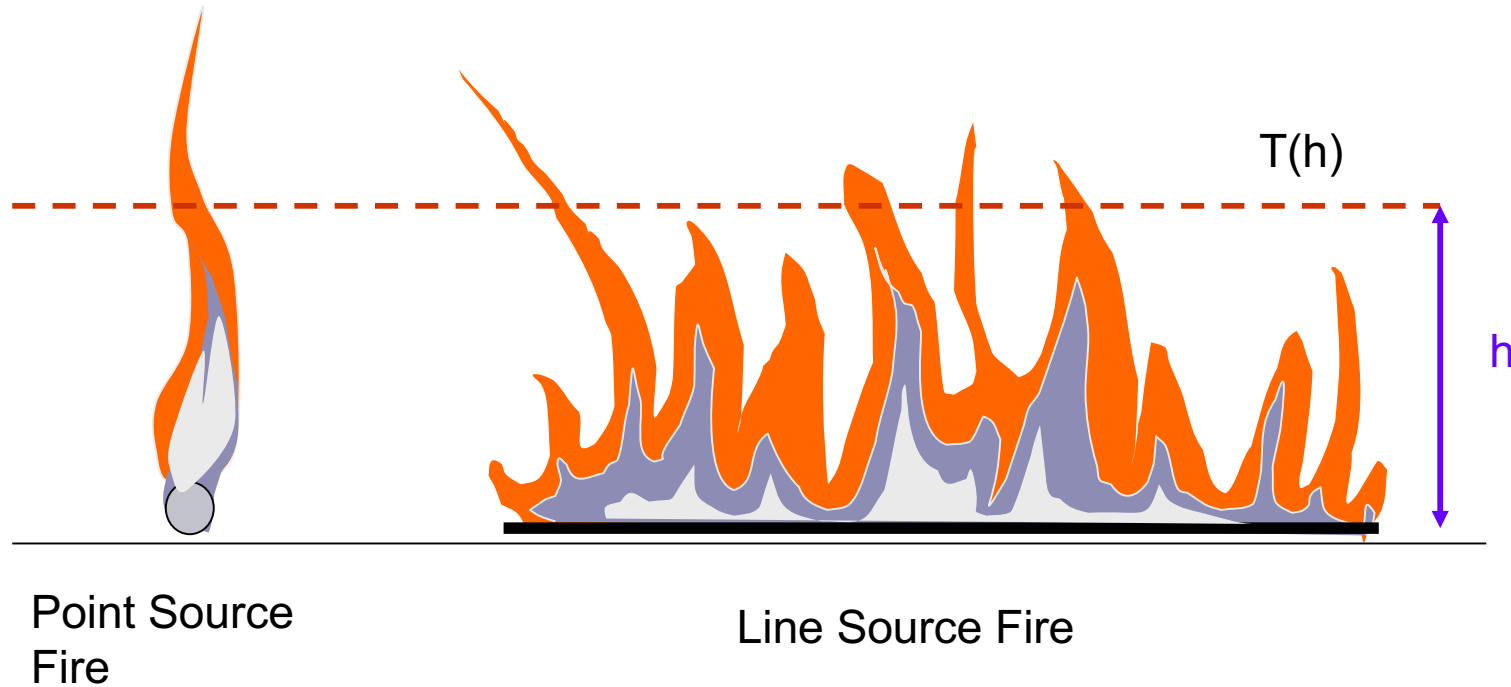
Homogeneous (L): Mean=457.6, Std=15.6, 5th Percentile=437.5, 95th Percentile=479.7
Non-Homogeneous (R): Mean=474.3, Std=48.8, 5th Percentile=400.4, 95th Percentile=559.4



DEVIATION FROM INTENDED USE

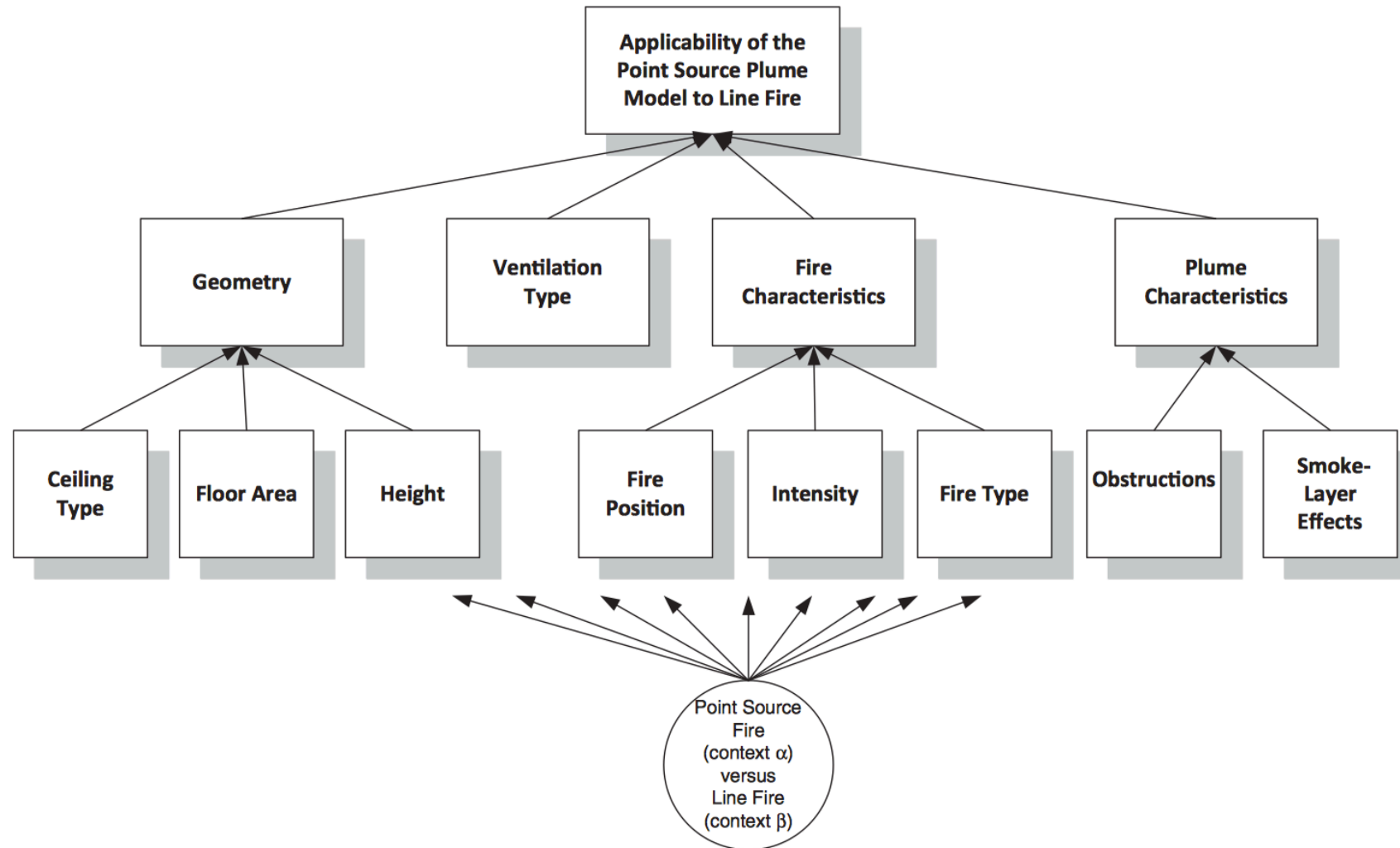


APPLICABILITY OF A MODEL



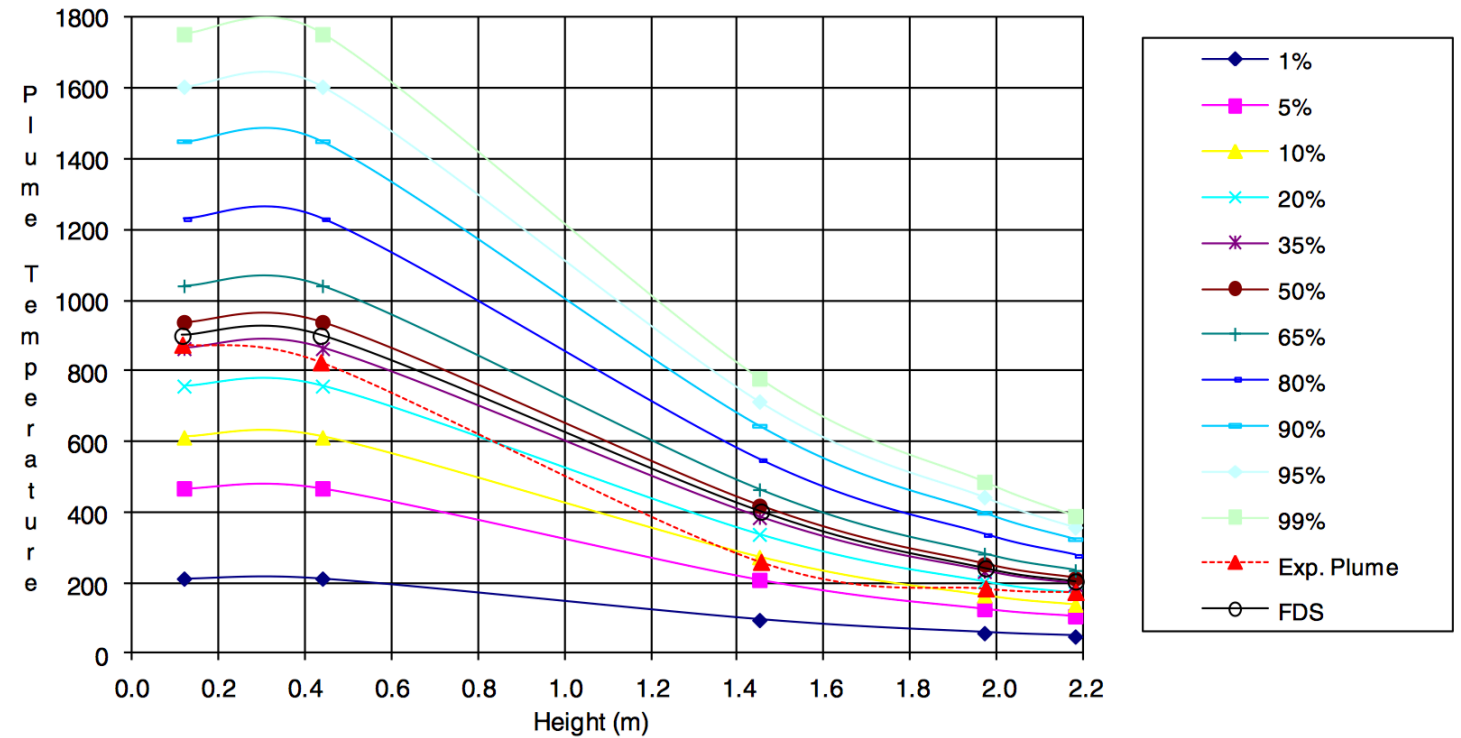
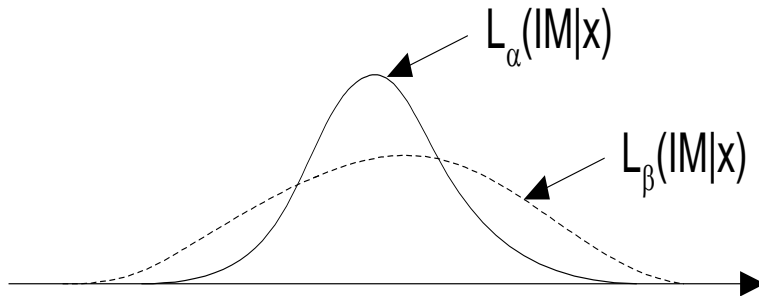
Predicting Fire Plume Temperature of a
Line Source Using *Point Source* Model

POINT SOURCE FIRE MODEL X LINE FIRE SOURCE MODEL



LINE FIRE PLUME TEMPERATURE

$$L_{\beta} = [L_{\alpha}]^{\beta}$$

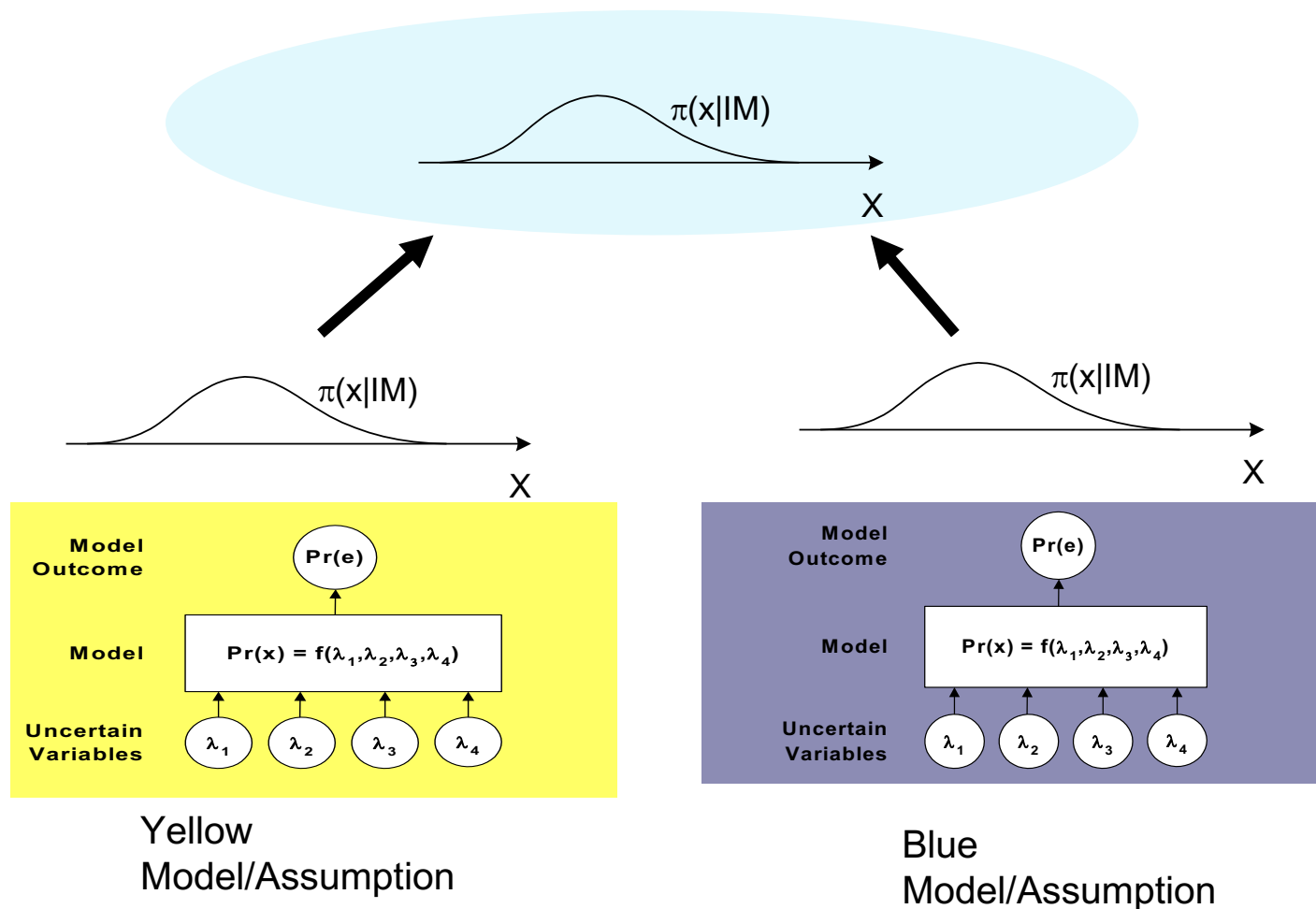


CHALLENGES AHEAD

UNCERTAINTY IS UNCERTAINTY?

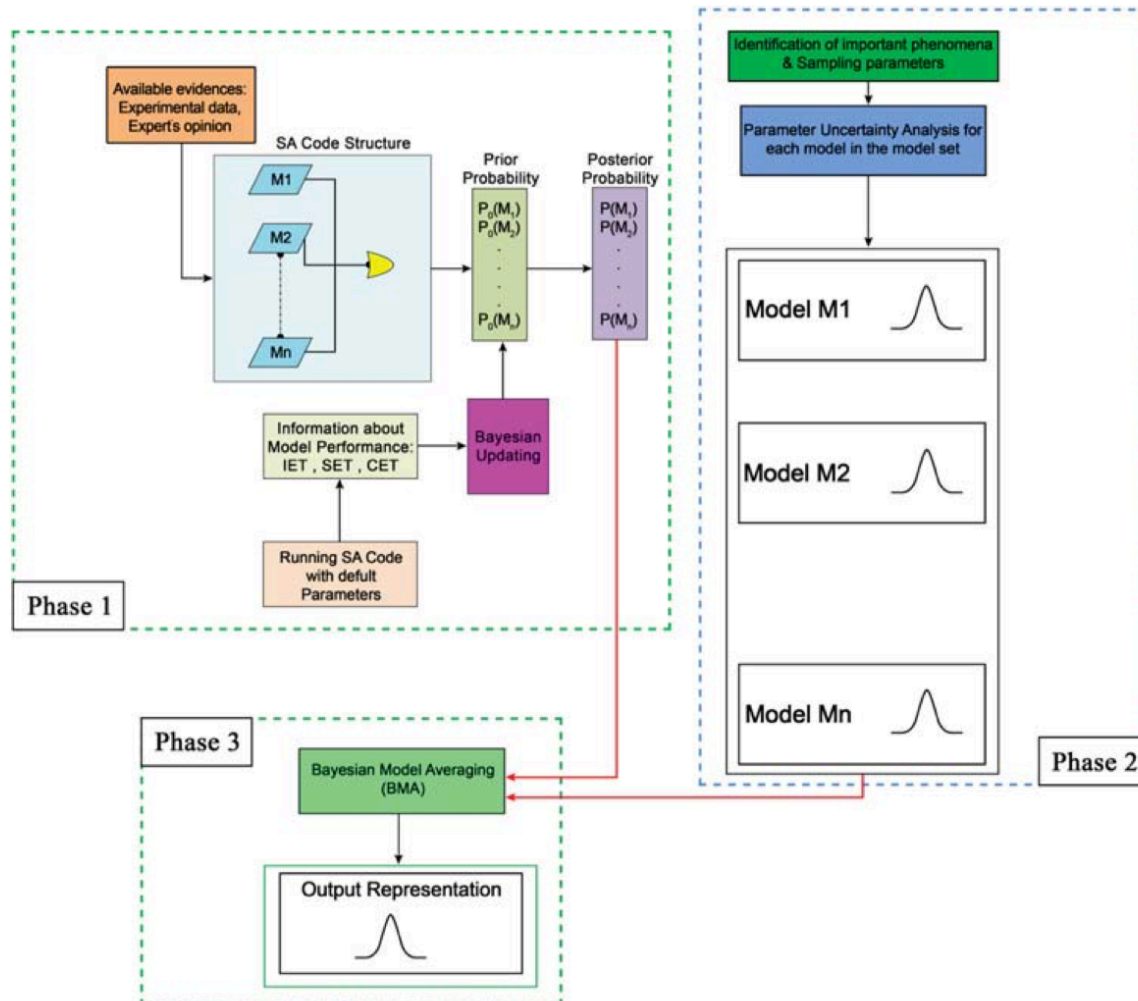
- Many believe that there is only one kind of uncertainty stemming from our lack of knowledge concerning reality
- “Let $p_0(n|t)$ be the true distribution of the number of events in $[0,t]$, obtained by considering an infinite number of activities similar to the one considered” (T. Bjerga et al., 2014)
- When analyzing complex phenomena:
 - Epistemic – practically reducible (by collecting more data and increasing our knowledge of the phenomenon in question)
 - Aleatory – practically irreducible (due to level of modeling detail, limitation of resources, limitation in current state of the art)

ALTERNATIVE MODELS



- Gaps in knowledge about relevant phenomena
- Approximations
- Quality of implementation
- This can lead to alternative assumptions on model structure giving raise to multiple models

SUBMODELS UNCERTAINTY – COMPUTATIONAL CODE



- Model uncertainty in severe accident analysis:

- Probability of best model based on Bayesian additive error model
- Use of performance data
- Multiple independent submodels
- Model uncertainty due to multiple submodels via BMA

Hoseyni and Pourgol-Mohammad, 2016

DEPENDENCY AMONG MODELS

- Models are likely to share some common theoretical principles as they are representations of the same reality
- Models may be subject to same common implementation procedures such as mathematical approximations and numerical techniques
- Models may have been conceptualized and implemented by individuals sharing the same basic training and knowledge
- As a result of sharing similar modeling processes, models might have common structural elements such as similarities in form and common sets of parameters
 - They would then share, to some degree, available information sources and some of their inputs

HEAT RELEASE RATE

- Heat Release Rate (HRR) in an enclosure fire:

$$Q = Q_o e^{\left(\frac{t}{\tau_g}\right)} \quad Q = Q_p \left(\frac{t}{\tau_g}\right)^2$$

- Copulas based quantification:
 - Likelihood function in terms of the Frank's copula

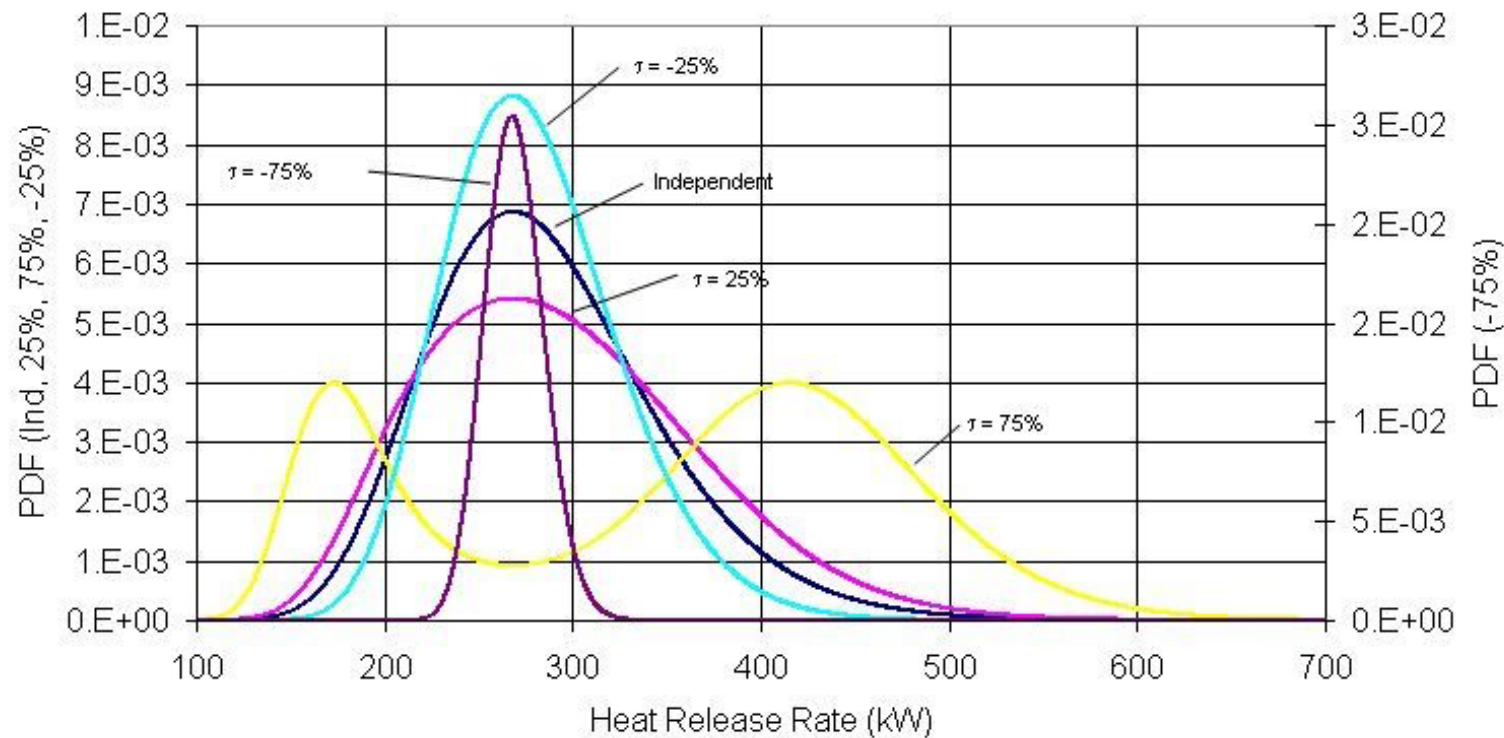
$$L(Q_1, Q_2 | Q) = \log_{\alpha} \left[1 + \frac{(\alpha^{F_1(Q_1|Q)} - 1)(\alpha^{F_2(Q_2|Q)} - 1)}{\alpha - 1} \right]$$

- Assuming multiplicative error:

$$f_i(Q_i | Q) = \frac{1}{\sqrt{2\pi}\sigma_i Q_i} e^{-\frac{1}{2} \left(\frac{\ln Q_i - (\ln Q + \ln b_i)}{\sigma_i} \right)^2}$$

MODEL UNCERTAINTY IN HEAT RELEASE RATE

- At $t = 200\text{s}$, we have $Q_1 = 193\text{ kW}$ and $Q_2 = 347\text{ kW}$



ACCOUNTING FOR THE UNKNOWN AND UNEXPECTED (I)

- What if our models are out of touch with reality
- The possibility that due to some unforeseen conditions (upset events) the real value could fall totally out of the range of model predictions
- Events associated with changes in natural, socio-economic, and political systems:
 - Wars
 - Sudden change of governments
 - Climate change
 -

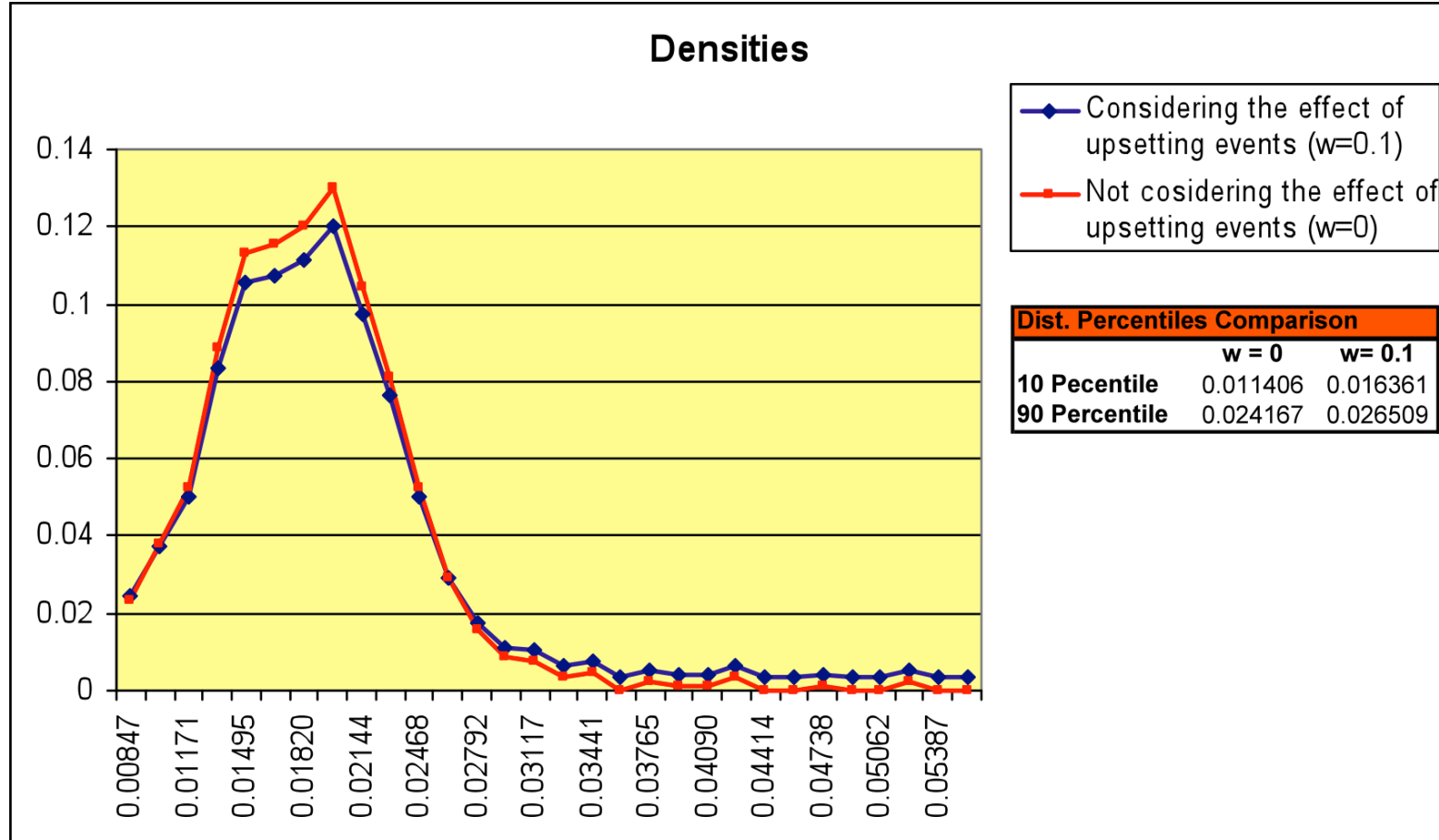
ACCOUNTING FOR THE UNKNOWN AND UNEXPECTED (II)

$$\pi'(p^{True} | p^{Estimate}, E) = (1 - w) * \pi(p^{True} | p^{Estimate}, E) + w * g(p^{True})$$

Where:

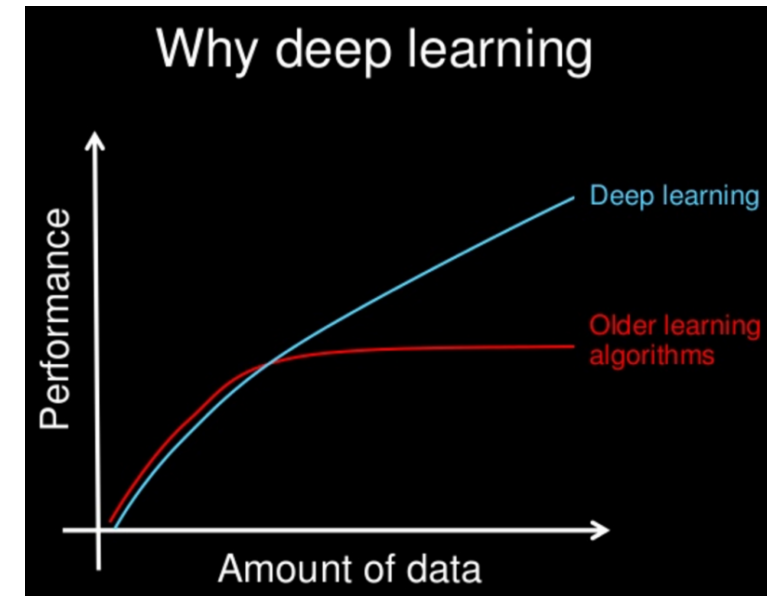
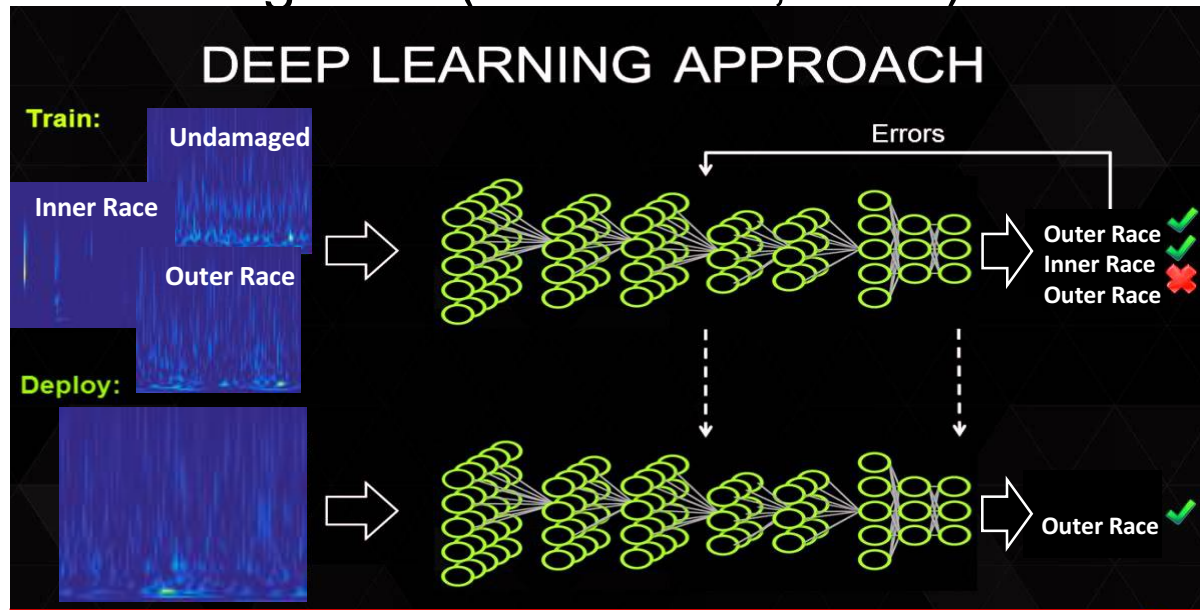
- “w” : relative frequency of “upset event”
- $\pi(p^{True} | p^{Estimate}, E)$: posterior distribution of default probability in the absence of upsetting events
- $g(p^{True})$: distribution of default probability in the case of occurrence of upset events
 - Uniform, non-informative

Example: Default Probability Uncertainty Distribution for 2006 (with Effect of Upset Events)



DEEP LEARNING BASED PHM

- Deep learning has attracted tremendous attention from researchers in fields such as physics, biology, and manufacturing, to name a few (Baldi et al., 2014; Anjos et al., 2015; Bergmann et al., 2014)
- It has recently been introduced in reliability
 - Diagnosis (Droguett et al., 2017; Zhou et al., 2017)
 - Prognosis (Babu et al., 2016)

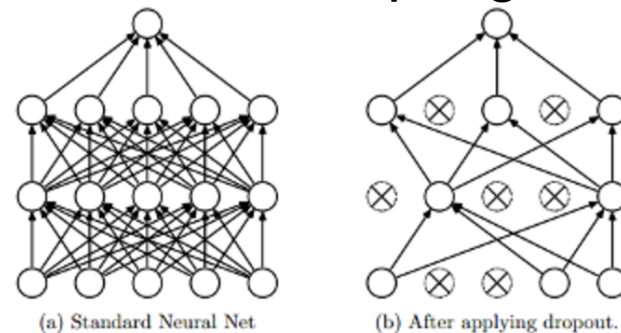


DRAWBACKS OF STANDARD DEEP LEARNING

- Compute point estimates
- Deep NNs make overly confident decisions about the correct class, prediction or action
- Deep NNs are prone to overfitting
- No uncertainty quantification
 - Serious limitation for decision making in critical applications such as safety, medical

BAYESIAN NEURAL NETWORKS AND DROPOUT

- Not **scalable** for modern applications and massive data sets
- Dropout:
 - Empirical technique used to avoid overfitting
 - It multiplies hidden activations by Bernoulli distributed random variables which take the value 1 with probability p and 0 otherwise
 - Randomly "drop out" hidden units and their connections during training time to prevent hidden units from co-adapting too much



Srivastava, Hinton, Krizhevsky, Sutskever, Salakhutdinov.

Dropout: A Simple Way to Prevent Neural Networks from Overfitting,
J. Machine Learning Research (2014)

Dropout Neural Net Model. **Left:** A standard neural net with 2 hidden layers. **Right:** An example of a thinned net produced by applying dropout to the network on the left. Crossed units have been dropped.

BAYESIAN DEEP LEARNING WITH MC DROPOUT*

- Requires applying dropout at every weight layer at test time
- For input x^* the predictive distribution for output y^* is:

$$q(y^* | x^*) = \int p(y^* | x^*, \omega) \cdot q(\omega) d\omega$$

- MC Dropout averages over N forward passes through the network at test time
- MC Dropout corresponds to model averaging
 - Results in estimation of the model output uncertainty
 - Model uncertainty and parameter uncertainty are comingled

*Y. Gal, Z. Ghahramani. Dropout as a Bayesian Approximation: Representing Model Uncertainty in Deep Learning. Proceedings of the 33rd International Conference on Machine Learning, New York, NY, USA, 2016

CONCLUSIONS (I)

- Risk assessments are often model-based
- Not taking into account model uncertainty can underestimate the amount of uncertainty
- Understanding the fundamentals is a must
 - Research efforts are needed to explore fundamentals
 - Help in developing better quantification methods

CONCLUSIONS (II)

- Operationalization of model uncertainty poses various challenges:
 - Multiple and dependent models
 - Time varying dependences
 - Effective ways to disentangle model and parameter uncertainties
 - Submodels, computer codes
 - Bayesian approaches are usually too expensive
 - Explore other alternatives for model uncertainty representation (e.g., evidence theory)

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THANK YOU!